

## Lecture 7. Support Vector Machine II

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The major references of this lecture are [2, 1].

## 1 The Problem Settings

Recall from the last lecture that, we consider the problem as follows.

$$\begin{aligned} \min_{\mathbf{x}} f(\mathbf{x}) & \quad (1) \\ \text{s.t. } \mathbf{g}(\mathbf{x}) & \leq 0, \\ \mathbf{h}(\mathbf{x}) & = 0, \\ \mathbf{x} & \in X, \end{aligned}$$

where  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $\mathbf{g} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ , and  $\mathbf{h} : \mathbb{R}^n \rightarrow \mathbb{R}^p$  are all continuously differentiable. The problem in (1) is the so-called primal problem, and its feasible set is denoted by

$$D_0 = \{\mathbf{x} \in \mathbb{R}^n : \mathbf{g}(\mathbf{x}) \leq 0, \mathbf{h}(\mathbf{x}) = 0, \mathbf{x} \in X\}.$$

## 2 Lagrange Duality

### 2.1 The dual problem

We introduce the dual function, which is defined for  $(\lambda, \mu) \in \mathbb{R}^{m+p}$  by

$$q(\lambda, \mu) = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda, \mu).$$

The dual problem is

$$\begin{aligned} \max q(\lambda, \mu), \\ \text{s.t. } \lambda \geq 0. \end{aligned}$$

The dual optimal value is defined by

$$q^* = \sup_{\{(\lambda, \mu) : \lambda \geq 0\}} q(\lambda, \mu). \quad (2)$$

**Remark 1.** Recall that, for each  $(\lambda, \mu)$ , the value of  $\inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda, \mu)$  is indeed the *interception* of the hyperplane—that has normal  $(\lambda, \mu, 1)$  and supports the set

$$S = \{(\mathbf{g}(\mathbf{x}), \mathbf{h}(\mathbf{x}), f(\mathbf{x}) : \mathbf{x} \in X \subseteq \mathbb{R}^n)\}$$

from below—with the vertical axis. Thus, solving the dual problem corresponds to find the supremum of this interception.

Notice that,  $L(\mathbf{x}, \lambda, \mu)$  can be unbounded from below for some  $(\lambda, \mu)$ . If this is the case, we have  $q(\lambda, \mu) = -\infty$ . Thus, we introduce the domain of  $q$ , which is the set for which  $q(\lambda, \mu)$  is finite:

$$\mathbf{dom} q = \{(\lambda, \mu) : q(\lambda, \mu) > -\infty\}.$$

We can similarly define the *dual feasible set* by

$$D_1 = \{(\lambda, \mu) : \lambda \geq 0\} \cap \mathbf{dom} q = \{(\lambda, \mu) : \lambda \geq 0, q(\lambda, \mu) > -\infty\}.$$



**Remark 2.** We do not require that  $\lambda \geq 0$  for the points in  $\mathbf{dom}(q)$ .

**Proposition 1.** *The domain of  $q$  is convex and  $q$  is concave over  $\mathbf{dom}(q)$ .*

*Proof.* We first show that  $\mathbf{dom}(q)$  is convex.

Suppose that  $q(\lambda_1, \mu_1)$  and  $q(\lambda_2, \mu_2)$  are finite and  $(\lambda_1, \mu_1) \neq (\lambda_2, \mu_2)$ . Let  $\theta \in [0, 1]$ .

$$\begin{aligned} q(\theta\lambda_1 + (1-\theta)\lambda_2, \theta\mu_1 + (1-\theta)\mu_2) &= \inf_{\mathbf{x} \in X} L(\mathbf{x}, \theta\lambda_1 + (1-\theta)\lambda_2, \theta\mu_1 + (1-\theta)\mu_2) \\ &= \inf_{\mathbf{x} \in X} \theta L(\mathbf{x}, \lambda_1, \mu_1) + (1-\theta)L(\mathbf{x}, \lambda_2, \mu_2) \\ &\geq \inf_{\mathbf{x} \in X} \theta L(\mathbf{x}, \lambda_1, \mu_1) + \inf_{\mathbf{x} \in X} (1-\theta)L(\mathbf{x}, \lambda_2, \mu_2) \\ &= \theta q(\lambda_1, \mu_1) + (1-\theta)q(\lambda_2, \mu_2) \\ &> -\infty. \end{aligned}$$

Thus, we have  $\mathbf{dom}(q)$  is convex.

The concavity of  $q$  can easily be seen by noting that  $q$  is the infimum of a set of linear functions of  $(\lambda, \mu)$ .  $\square$

## 2.2 Weak duality

**Theorem 1. Weak Duality Theorem** *We have*

$$q^* \leq f^*. \quad (3)$$

*Proof.* For any  $(\lambda, \mu)$ , we have

$$q(\lambda, \mu) = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda, \mu) \leq \inf_{\mathbf{x} \in D} L(\mathbf{x}, \lambda, \mu) \leq \inf_{\mathbf{x} \in D} f(\mathbf{x}) = f^*.$$

Thus,

$$q^* = \sup_{\{(\lambda, \mu): \lambda \geq 0\}} q(\lambda, \mu) \leq f^*.$$

$\square$

**Definition 1.** Duality gap is defined by

$$f^* - q^*.$$

**Remark 3.** Duality gap is a commonly used termination condition for a set of optimization algorithms.

**Proposition 2.**

1. *If there is no duality gap, the set of geometric multipliers is equal to the set of optimal dual solutions.*
2. *If there is duality gap, the set of geometric multipliers is empty.*

*Proof.* Recall the definition of geometric multipliers that, if  $(\lambda^*, \mu^*)$  belongs to a set of geometric multipliers, we have  $\lambda^* \geq 0$  and

$$\inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda^*, \mu^*) = f^*.$$

On the other hand, notice that, the left hand side of the above equation is indeed  $q(\lambda^*, \mu^*)$ .



1. Suppose that  $f^* = q^*$ .

We first show that the set of geometric multipliers belongs to the set of optimal dual solutions. Let  $(\lambda^*, \mu^*)$  be one of the geometric multipliers. Thus

$$f^* = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda^*, \mu^*) = q(\lambda^*, \mu^*) \leq \sup_{\{(\lambda, \mu): \lambda \geq 0\}} q(\lambda, \mu) = q^*.$$

As  $f^* = q^*$ , we can see that

$$q(\lambda^*, \mu^*) = \sup_{\{(\lambda, \mu): \lambda \geq 0\}} q(\lambda, \mu).$$

This implies that the geometric multiplier  $(\lambda^*, \mu^*)$  is one of the optimal dual solutions.

We next show that the set of optimal dual solutions belongs to the set of geometric multipliers. Let  $(\lambda^*, \mu^*)$  be one of the optimal dual solutions. Then

$$q(\lambda^*, \mu^*) = \sup_{\{(\lambda, \mu): \lambda \geq 0\}} q(\lambda, \mu) = q^*.$$

In view of  $f^* = q^*$ , we can see that

$$f^* = q^* = q(\lambda^*, \mu^*) = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda^*, \mu^*).$$

This implies that  $(\lambda^*, \mu^*)$  is one of the geometric multipliers. The proof is complete.

2. Suppose that  $f^* - q^* > 0$ . This implies that, for any  $(\lambda, \mu)$ ,

$$q(\lambda, \mu) = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda, \mu) \leq q^* < f^*.$$

Therefore, there is no  $(\lambda^*, \mu^*)$ , such that  $q(\lambda, \mu) = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda, \mu) = f^*$ . Thus, the set of geometric multipliers is empty.

□

**Remark 4.** If we can find a geometric multiplier, then there is no duality gap. However, the converse is not true.

### 2.3 Primal and dual optimal solutions

**Proposition 3. Optimality Conditions** A pair  $\mathbf{x}^*$  and  $(\lambda^*, \mu^*)$  is an optimal solution and geometric multiplier pair if and only if

$$\mathbf{x}^* \in X, \mathbf{g}(\mathbf{x}^*) \leq 0, \mathbf{h}(\mathbf{x}^*) = 0, \quad (\text{Primal Feasibility}), \quad (4)$$

$$\lambda^* \geq 0, \quad (\text{Dual Feasibility}), \quad (5)$$

$$\mathbf{x}^* \in \underset{\mathbf{x} \in X}{\text{argmin}} L(\mathbf{x}, \lambda^*, \mu^*), \quad (\text{Lagrangian Optimality}), \quad (6)$$

$$\lambda_i^* g_i(\mathbf{x}^*) = 0, \quad i = 1, \dots, m, \quad (\text{Complementary Slackness}). \quad (7)$$

*Proof.*



1.  $\Rightarrow$  Suppose that  $\mathbf{x}^*$  and  $(\lambda^*, \mu^*)$  is an optimal solution and geometric multiplier pair. Then, the primal feasibility and dual feasibility hold.

Moreover,

$$f(\mathbf{x}^*) = f^* = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda^*, \mu^*) \leq L(\mathbf{x}^*, \lambda^*, \mu^*) \leq f(\mathbf{x}^*),$$

which implies the Lagrangian optimality and the complementary slackness.

2.  $\Leftarrow$  Suppose that the conditions in (4) to (7) hold. Then

$$f(\mathbf{x}^*) = L(\mathbf{x}^*, \lambda^*, \mu^*) = \min_{\mathbf{x} \in X} L(\mathbf{x}, \lambda^*, \mu^*) \leq \inf_{\mathbf{x} \in D_0} L(\mathbf{x}, \lambda^*, \mu^*) \leq \inf_{\mathbf{x} \in D_0} f(\mathbf{x}) \leq f(\mathbf{x}^*),$$

which implies that  $\mathbf{x}^*$  is the optimal solution and  $(\lambda^*, \mu^*)$  is the geometric multiplier. □

**Proposition 4. Saddle Point Theorem** *A pair  $\mathbf{x}^*$  and  $(\lambda^*, \mu^*)$  is an optimal solution-geometric multiplier pair if and only if  $\mathbf{x}^* \in X$ ,  $\lambda^* \geq 0$ , and  $(\mathbf{x}^*, \lambda^*, \mu^*)$  is a saddle point of the Lagrangian, in the sense that*

$$L(\mathbf{x}^*, \lambda, \mu) \leq L(\mathbf{x}^*, \lambda^*, \mu^*) \leq L(\mathbf{x}, \lambda^*, \mu^*), \forall \mathbf{x} \in X, \lambda \geq 0, \mu \in \mathbb{R}^p. \quad (8)$$

*Proof.*

1.  $\Rightarrow$  As the pair  $\mathbf{x}^*$  and  $(\lambda^*, \mu^*)$  is an optimal solution-geometric multiplier pair, we have (4) to (7) hold. Clearly, we can see that  $\mathbf{x}^* \in X$ ,  $\lambda^* \geq 0$ , and the Lagrangian optimality in (6) implies that

$$L(\mathbf{x}^*, \lambda^*, \mu^*) \leq L(\mathbf{x}, \lambda^*, \mu^*), \forall \mathbf{x} \in X.$$

Moreover, in view of the definition of geometric multiplier, we have

$$f^* = \inf_{\mathbf{x} \in X} L(\mathbf{x}, \lambda^*, \mu^*) = L(\mathbf{x}^*, \lambda^*, \mu^*).$$

Thus, combining the feasibility of  $\mathbf{x}^*$  and  $\lambda \geq 0$  leads to

$$L(\mathbf{x}^*, \lambda, \mu) = f(\mathbf{x}^*) + \langle \lambda, \mathbf{g}(\mathbf{x}^*) \rangle + \langle \mu, \mathbf{h}(\mathbf{x}^*) \rangle \leq f(\mathbf{x}^*) = L(\mathbf{x}^*, \lambda^*, \mu^*),$$

which completes the proof.

2.  $\Leftarrow$  In view of Proposition 3, it suffices to show that (4) and (7) hold. The left half of the saddle point property of the Lagrangian in (8) implies that

$$\begin{aligned} L(\mathbf{x}^*, \lambda, \mu) &\leq L(\mathbf{x}^*, \lambda^*, \mu^*), \forall \lambda \geq 0, \\ \Rightarrow f(\mathbf{x}^*) + \langle \lambda, \mathbf{g}(\mathbf{x}^*) \rangle + \langle \mu, \mathbf{h}(\mathbf{x}^*) \rangle &\leq L(\mathbf{x}^*, \lambda^*, \mu^*), \forall \lambda \geq 0. \end{aligned}$$

In other words,  $L(\mathbf{x}^*, \lambda, \mu)$  is upper bounded for any  $\lambda \geq 0$ . Consequently, we have

$$\mathbf{g}(\mathbf{x}^*) \leq 0, \mathbf{h}(\mathbf{x}^*) = 0,$$

i.e., the primal feasibility (4) holds (otherwise  $L(\mathbf{x}^*, \lambda, \mu)$  can not be upper bounded).



To show that the complementary slackness in (7) holds, we combine the primal feasibility of  $\mathbf{x}^*$  and left half of (8)

$$f(\mathbf{x}^*) + \langle \lambda, \mathbf{g}(\mathbf{x}^*) \rangle \leq f(\mathbf{x}^*) + \langle \lambda^*, \mathbf{g}(\mathbf{x}^*) \rangle, \forall \lambda \geq 0,$$

$$\xrightarrow{\lambda \rightarrow 0} \langle \lambda^*, \mathbf{g}(\mathbf{x}^*) \rangle = \sum_{i=1}^m \lambda_i^* g_i(\mathbf{x}^*) \geq 0.$$

On the other hand, in view of the facts that  $\lambda^* \geq 0$  and  $\mathbf{g}(\mathbf{x}^*) \leq 0$ , we have

$$\lambda_i^* g_i(\mathbf{x}^*) \leq 0, i = 1, \dots, m.$$

All together, we have

$$\lambda_i^* g_i(\mathbf{x}^*) = 0, i = 1, \dots, m.$$

Thus, the complementary slackness holds and the proof is complete. □

## 2.4 Strong duality

We discuss conditions that ensure the duality gap is zero.

**Proposition 5. Strong Duality Theorem - Linear Constraints** *Consider the problem in (1). Suppose that  $f$  is convex,  $X$  is a polyhedron (that is,  $X = \{\mathbf{x} : \langle \mathbf{a}_i, \mathbf{x} \rangle \leq b_i, i = 1, \dots, r\}$ ), and the optimal value  $f^*$  is finite. Then, there is no duality gap and there exists at least one geometric multiplier.*

**Proposition 6. Linear and Quadratic Programming Duality** *Consider the problem in (1). Suppose that  $f$  is convex quadratic,  $X$  is a polyhedron, and the optimal value  $f^*$  is finite. Then, the primal and dual problems have optimal solutions, and the duality gap is 0.*

## 3 The Dual Problem of SVM

Recall that the soft margin SVM takes the form of

$$\min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^n \xi_i, \tag{9}$$

$$\text{s.t. } y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1 - \xi_i, i \in [n],$$

$$\xi_i \geq 0, i \in [n].$$

By Proposition (6), the strong duality holds.

To find the dual problem of (9), we first construct the Lagrangian:

$$L(\mathbf{w}, b, \xi, \alpha, \mu) = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^n \xi_i + \sum_{i=1}^n \alpha_i (1 - \xi_i - y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b)) - \sum_{i=1}^n \mu_i \xi_i,$$

where  $\alpha_i, \mu_i \geq 0, i = 1, \dots, n$ .

We next find the dual function:

$$q(\alpha, \mu) = \inf_{\mathbf{w}, b, \xi} L(\mathbf{w}, b, \xi, \alpha, \mu) \quad (10)$$

$$= \inf_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^n \alpha_i y_i \langle \mathbf{w}, \mathbf{x}_i \rangle \quad (11)$$

$$+ \inf_b -b \sum_{i=1}^n \alpha_i y_i \quad (12)$$

$$+ \inf_{\xi} \sum_{i=1}^n (C - \alpha_i - \mu_i) \xi_i. \quad (13)$$

For fixed  $(\alpha, \mu)$ , let  $(\hat{\mathbf{w}}, \hat{b}, \hat{\xi})$  be the optimal solution to the above problem. The first order optimal condition implies that

$$\nabla_{\mathbf{w}} L(\mathbf{w}, b, \xi, \alpha, \mu)|_{\mathbf{w}=\hat{\mathbf{w}}} = 0 \Rightarrow \hat{\mathbf{w}} - \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i = 0,$$

$$\nabla_b L(\mathbf{w}, b, \xi, \alpha, \mu)|_{b=\hat{b}} = 0 \Rightarrow - \sum_{i=1}^n \alpha_i y_i = 0,$$

$$\nabla_{\xi_i} L(\mathbf{w}, b, \xi, \alpha, \mu)|_{\xi_i=\hat{\xi}_i} = 0 \Rightarrow C - \alpha_i - \mu_i = 0.$$

Plugging the above equations into Eq. (10) leads to

$$q(\alpha, \mu) = -\frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle + \sum_{i=1}^n \alpha_i. \quad (14)$$

Thus, the dual problem of the soft margin SVM in (9) is

$$\begin{aligned} \max_{\alpha} & -\frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle + \sum_{i=1}^n \alpha_i \\ \text{s.t.} & \sum_{i=1}^n \alpha_i y_i = 0, \\ & C - \alpha_i - \mu_i = 0, \\ & \alpha_i \geq 0, \\ & \mu_i \geq 0, i = 1, \dots, n. \end{aligned}$$

By simple algebraic manipulation, we can remove  $\mu$  from the problem, that is

$$\begin{aligned} \min_{\alpha} & \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle - \sum_{i=1}^n \alpha_i \\ \text{s.t.} & \sum_{i=1}^n \alpha_i y_i = 0, \\ & \alpha_i \in [0, C], i = 1, \dots, n. \end{aligned} \quad (15)$$



**Proposition 7.** Let  $\alpha^*$  be one of the optimal solutions to (15). Suppose that  $\alpha_k^*$  is one of the entries of  $\alpha^*$  and  $\alpha_k^* \in (0, C)$ , then we can find a primal optimal solution by

$$\mathbf{w}^* = \sum_{i=1}^n \alpha_i^* y_i \mathbf{x}_i,$$
$$b^* = y_k - \langle \mathbf{w}^*, \mathbf{x}_k \rangle.$$



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## References

- [1] D. P. Bertsekas. *Nonlinear Programming, 3ed.* Athena Scientific, 2016.
- [2] M. Mohri, A. Rostamizadeh, and A. Talwalkar. *Foundations of Machine Learning, 2ed.* The MIT Press, 2018.